





## **Digital Image Processing**

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## Topic

- Background
- Basic of multiresolution analysis
- A tour of wavelets







## Background

- Objects are formed by connected regions of similar texture and intensity levels.
- If the objects are small in size or low in contrast, we normally examine them at high resolutions; if they are large in size or high in contrast, a coarse view is required.

**Multiresolution processing** 





## Background

### Image Pyramids

An image pyramid is a collection of decreasing resolution images arranged in the shape of a pyramid

The base of the pyramid contains a high-resolution representation of the image being processed; the apex contains a low-resolution approximation.





Idea: Represent NxN image as a "pyramid" of 1x1, 2x2, 4x4,..., 2<sup>k</sup>x2<sup>k</sup> images (assuming N=2<sup>k</sup>)



### Known as a Gaussian Pyramid [Burt and Adelson, 1983]

- In computer graphics, a *mip map* [Williams, 1983]
- A precursor to wavelet transform





## **Image Pyramids**







## **Image Pyramids**

- Gaussian Pyramid
  - Approximation pyramid
- Laplacian Pyramid
  - Prediction residual pyramid

a b

FIGURE 7.3 Two image pyramids and their histograms: (a) an approximation pyramid; (b) a prediction residual pyramid.







## Gaussian pyramid construction

### Step:

### Repeat {

- Filter
- Subsample

} Until minimum resolution reached

• can specify desired number of levels (e.g., 3-level pyramid)

The whole pyramid is only 4/3 the size of the original image!





## Laplacian pyramid construction

### • Created from Gaussian pyramid by subtraction







## What are they good for?

### Improve Search

- Search over translations
  - Like homework
  - Classic coarse-to-fine strategy
- Search over scale
  - Template matching
  - E.g. find a face at different scales

### Precomputation

- Need to access image at different blur levels
- Useful for texture mapping at different resolutions
- Image Processing
  - Editing frequency bands separately
  - E.g. image blending... next time!





## Background

Subband Coding

Another important imaging technique with ties to multiresolution analysis is subband coding

In subband coding, an image is decomposed into a set of bandlimited components, called subbands











• For perfect reconstruction, the impulse responses of the synthesis and analysis filters must be related in one of the following two ways:

$$g_0(n) = (-1)^n h_1(n)$$
  
 $g_1(n) = (-1)^{n+1} h_0(n)$ 

• or

$$g_{0}(n) = (-1)^{n+1} h_{1}(n)$$
$$g_{1}(n) = (-1)^{n} h_{0}(n)$$







• The impulse responses of the synthesis and analysis filters can be shown to satisfy the following biorthogonality condition

$$\langle h_i(2n-k), g_j(k) \rangle = \delta(i-j)\delta(n), \quad i, j = \{0, l\}$$

 Of special interest in subband coding
 – and in the development of the fast wavelet transform
 – are filters that move beyond biorthogonality and require

$$\langle g_i(n), g_j(n+2m) \rangle = \delta(i-j)\delta(m), \quad i, j = \{0, 1\}$$

which defines orthonormality for perfect reconstruction filter banks.





• Orthonormal filters can be shown to satisfy the following two conditions

$$g_{1}(n) = (-1)^{n} g_{0}(K_{even} - 1 - n)$$
  
$$h_{i}(n) = g_{i}(K_{even} - 1 - n), \quad i = \{0, 1\}$$







• 1-D orthonormal and biorthogonal filters can be used as 2-D separable filters for the processing of images.







### Example 7.2 a four-band subband coding of vase

п	$g_0(n)$
0	0.23037781
1	0.71484657
2	0.63088076
3	-0.02798376
4	-0.18703481
5	0.03084138
6	0.03288301
7	-0.01059740







### Example 7.2 a four-band subband coding of vase







### Example 7.2 a four-band subband coding of vase







## Background

- The Haar Transform
  - Haar transform is a special wavelet transform
  - Its basis functions are the oldest and simplest orthonormal wavelets
  - Haar transform can be expressed in a matrix form

 $T = HFH^T$ 

*F* is an  $N \times N$  image matrix *H* is an  $N \times N$  transformation matrix *T* is the resulting  $N \times N$  transform





• Basis functions of Haar transform (continuous)







- All of the basis functions are rectangular impulse pairs except  $h_0(z)$
- The impulse pairs have different width, height and positions
- Width of nonzero region is descending

$$1 \to \frac{1}{2} \to \frac{1}{4} \to \frac{1}{8} \to \dots$$

Height of nonzero region is ascending

$$\frac{1}{\sqrt{N}} \to \frac{\sqrt{2}}{\sqrt{N}} \to \frac{2}{\sqrt{N}} \to .$$

 The basis functions have the same characters as those of wavelet transform





Basis functions of Haar transform (discrete)







- The *i*th row of an N by N Haar transformation matrix contains the elements of  $h_i(z)$  for  $z = \frac{0}{N}, \frac{1}{N}, \frac{2}{N}, \dots, \frac{N-1}{N}$
- 2×2 transformation matrix is

$$H_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

• 4×4 transformation matrix is

$$H_4 = \frac{1}{\sqrt{4}} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 1 & -1 & -1 \\ 0\sqrt{2} & -\sqrt{2} & 0 & 0 \\ 0 & \sqrt{2} & -\sqrt{2} \end{bmatrix}$$





### • 8×8 transformation matrix is





- Transformation kernel is separable
- For N = 8, the basis functions are







• Example 7.3 Haar functions in a discrete wavelet transform.



a b c d

**FIGURE 7.10** (a) A discrete wavelet transform using Haar  $H_2$ basis functions. Its local histogram variations are also shown. (b)–(d) Several different approximations (64 × 64, 128 × 128, and 256 × 256) that can be obtained from (a).









• Expansion of a signal *f*(*x*) :

 $f(x) = \sum_{k} \alpha_{k} \phi_{k}(x) \qquad \begin{array}{l} \alpha_{k} : \text{ real-valued expansion coefficients} \\ \phi_{k}(x) : \text{ real-valued expansion functions} \end{array}$ 

 $\alpha_k = \left\langle \tilde{\phi}_k(x), f(x) \right\rangle = \int \tilde{\phi}_k^*(x) f(x) dx \quad \tilde{\phi}_k(x): \text{ the dual function of } \phi_k(x)$ 

If the expansion is unique, the  $\phi_k(x)$  are called basis functions.





If  $\{\phi_k(x)\}$  is an orthonormal basis for *V*, then  $\phi_k(x) = \tilde{\phi}_k(x)$ 

The function space of the expansion set  $\phi_k(x)$ :  $V = span_k \{\phi_k(x)\}$ 

If  $\{\phi_k(x)\}$  are not orthonormal but are an orthogonal basis for *V*, then the basis funcitons and their duals are called biorthogonal.

Biorthogonal: 
$$\left\langle \phi_{j}(x), \tilde{\phi}_{k}(x) \right\rangle = \delta_{jk} = \begin{cases} 0 & , j \neq k \\ 1 & , j = k \end{cases}$$

How to construct such orthonormal basis?





Scaling functions

 $\phi_{j,k}(x) = 2^{j/2} \phi(2^j x - k), \text{ for } k \in \mathbb{Z} \text{ and } \phi(x) \in L^2(\mathbb{R})$ 

The subspace spanned over k for any j:

$$V_j = span_k \left\{ \phi_{j,k}(x) \right\}$$







- Requirements of scaling function:
  - 1. The scaling function is orthogonal to its integer translates.
  - 2. The subspaces spanned by the scaling function at low scales are nested within those spanned at higher scales. That is  $V_{-\infty} \subset \cdots \subset V_{-1} \subset V_0 \subset V_1 \subset V_2 \subset \cdots \subset V_{\infty}$
  - 3. The only function that is common to all  $V_j$  is f(x) = 0That is  $V_{-\infty} = \{0\}$
  - 4. Any function can be represented with arbitrary precision. That is,  $V_{\infty} = \{L^2(\mathbf{R})\}$











Wavelet function

spans the difference between any two adjacent scaling subspaces  $V_j$  and  $V_{j+1}$ 

$$\psi_{j,k}(x) = 2^{j/2} \psi(2^j x - k)$$
 for all  $k \in \mathbb{Z}$  that spans the space  $W_j$   
where  $W_j = span_k \{ \psi_{j,k}(x) \}$ 

The wavelet function can be expressed as a weighted sum of shifted, double-resolution scaling functions. That is,

$$\psi(x) = \sum_{n} h_{\psi}(n) \sqrt{2}\phi(2x - n)$$

where the  $h_{\psi}(n)$  are called the wavelet function coefficients.

It can be shown that  $h_{\psi}(n) = (-1)^n h_{\phi}(1-n)$ 







We can express the space of all measurable, square-integrable function as

$$L^{2}(\mathbf{R}) = V_{0} \oplus W_{0} \oplus W_{1} \oplus W_{2} \oplus \cdots$$
  
or  
$$L^{2}(\mathbf{R}) = \cdots \oplus W_{-2} \oplus W_{-1} \oplus W_{0} \oplus W_{1} \oplus W_{2} \oplus \cdots$$





## A Tour of Wavelets





• The wavelet series expansions

$$f(x) = \sum_{k} c_{j_0}(k) \varphi_{j_0,k}(x) + \sum_{j=j_0}^{\infty} \sum_{k} d_j(k) \psi_{j_0,k}(x)$$

The expansion coefficients are calculated

$$c_{j_0}(k) = \left\langle f(x), \varphi_{j_0,k}(x) \right\rangle = \int f(x) \varphi_{j_0,k}(x) dx$$

and

$$d_{j}(k) = \left\langle f(x), \psi_{j,k}(x) \right\rangle = \int f(x) \psi_{j,k}(x) dx$$











The discrete wavelet transform

$$W_{\varphi}(j_{0},k) = \frac{1}{\sqrt{M}} \sum_{n} f(n) \varphi_{j_{0},k}(n)$$
$$W_{\psi}(j,k) = \frac{1}{\sqrt{M}} \sum_{n} f(n) \psi_{j,k}(n) \quad \text{for } j \ge j_{0}$$

• The complementary inverse DWT is

$$f(n) = \frac{1}{\sqrt{M}} \sum_{k} W_{\varphi}(j_{0},k) \varphi_{j_{0},k}(n) + \frac{1}{\sqrt{M}} \sum_{j=j_{0}}^{\infty} \sum_{k} W_{\psi}(j,k) \psi_{j,k}(n)$$





The continuous wavelet transform

$$W_{\psi}(s,\tau) = \int_{-\infty}^{\infty} f(x) \psi_{s,\tau}(x) dx$$

where

$$\Psi_{s,\tau}(x) = \frac{1}{\sqrt{s}} \Psi\left(\frac{x-\tau}{s}\right)$$

The inverse continuous wavelet transform

$$f(n) = \frac{1}{C_{\psi}} \int_{0}^{\infty} \int_{-\infty}^{\infty} W_{\psi}(s,\tau) \frac{\psi_{s,\tau}(x)}{s^{2}} ds d\tau$$

where

$$C_{\psi} = \int_{-\infty}^{\infty} \frac{\left|\Psi(\mu)\right|^2}{\left|\mu\right|} d\mu$$





### • The Mexican hat wavelet







- Computationally efficient implementation of the DWT
- The relationship between the coefficients of the DWT at adjacent scales
- Also called Mallat's herringbone algorithm
- Resembles the twoband subband coding scheme





The multiresolution refinement equation

 $\varphi(x) = \sum h_{\varphi}(n) \sqrt{2} \varphi(2x - n)$ 

Scaling x by 2<sup>j</sup>, translating it by k, and letting m=2k+n gives

$$\varphi\left(2^{j}x-k\right) = \sum_{m} h_{\varphi}\left(m-2k\right)\sqrt{2}\varphi\left(2^{j+1}x-n\right)$$

 A similar sequence of operations—beginning with Eq. (7.2-28) provides an analogous result

$$\psi(2^{j}x-k) = \sum_{m} h_{\psi}(m-2k)\sqrt{2}\varphi(2^{j+1}x-m)$$





• Now consider the wavelet series expansion coefficients of continuous function f(x), we get

$$d_{j}(k) = \sum_{m} h_{\psi}(m-2k)c_{j+1}(m)$$
$$c_{j}(k) = \sum_{m} h_{\varphi}(m-2k)c_{j+1}(m)$$

 When f(x) is discrete, the coefficients of the wavelet series expansion become the coefficient of the DWT

$$W_{\psi}(j,k) = \sum_{m} h_{\psi}(m-2k) W_{\varphi}(j+1,m)$$
$$W_{\varphi}(j,k) = \sum_{m} h_{\varphi}(m-2k) W_{\varphi}(j+1,m)$$





• We can write

 $W_{\psi}(j,k) = h_{\psi}(-n) \star W_{\varphi}(j+1,m)\Big|_{n=2k,k\geq 0}$  $W_{\varphi}(j,k) = h_{\varphi}(-n) \star W_{\varphi}(j+1,m)\Big|_{n=2k,k\geq 0}$ •  $W_{\psi}(j,n)$  $\star h_{\psi}(-n)$ 2↓ FIGURE 7.17 An FWT analysis  $W_{\varphi}(j+1,n) \bullet$ bank.  $\star h_{\varphi}(-n)$ •  $W_{\varphi}(j, n)$ 2↓











### Example 7.10 Computing a 1-D fast wavelet transform







• A fast inverse transform for the reconstruction of f(n) from the results of the forward transform can be formulated



• The *FWT*<sup>-1</sup> filter bank implements the computation

 $W_{\varphi}\left(j+1,k\right) = h_{\varphi}\left(k\right) * W_{\varphi}^{\uparrow 2}\left(j,k\right) + h_{\psi}\left(k\right) * W_{\psi}^{\uparrow 2}\left(j,k\right)\Big|_{k\geq 0}$ 











• Example 7.11 computing a 1-D inverse fast wavelet transform.



**FIGURE 7.22** Computing a two-scale inverse fast wavelet transform of sequence  $\{1, 4, -1.5\sqrt{2}, -1.5\sqrt{2}\}$  with Haar scaling and wavelet functions.





### • Time-frequency tilings for the basis functions



#### a b c

**FIGURE 7.23** Time-frequency tilings for the basis functions associated with (a) sampled data, (b) the FFT, and (c) the FWT. Note that the horizontal strips of equal height rectangles in (c) represent FWT scales.

 If you want precise information about, you must accept some vagueness about frequency, and vice versa. This is the Heisenberg uncertainty principle applied to information processing





- In two-dimensions, a two-dimensional scaling function, φ(x, y) and three two-dimensional wavelets, ψ<sup>H</sup>(x, y), ψ<sup>V</sup>(x, y), and ψ<sup>D</sup>(x, y), are required
- The separable function

$$\varphi(x, y) = \varphi(x)\varphi(y)$$

and separable, directionally sensitive wavelets

$$\psi^{H}(x, y) = \psi(x)\varphi(y)$$
  
$$\psi^{V}(x, y) = \varphi(x)\psi(y)$$
  
$$\psi^{D}(x, y) = \psi(x)\psi(y)$$





We first define the scaled and translated basis functions

$$\varphi_{j,m,n}(x, y) = 2^{j/2} \varphi \left( 2^{j} x - m, 2^{j} y - n \right),$$
  
$$\psi_{j,m,n}^{i}(x, y) = 2^{j/2} \psi^{i} \left( 2^{j} x - m, 2^{j} y - n \right), i = \{H, V, D\}$$

 Rather than an exponent, i is a superscript that assumes the values H, V, and D. the discrete wavelet transform of image f(x, y) of size M by N is then

$$W_{\varphi}(j_{0},m,n) = \frac{1}{\sqrt{MN}} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) \varphi_{j_{0},m,n}(x,y),$$
$$W_{\psi}^{i}(j,m,n) = \frac{1}{\sqrt{MN}} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) \psi_{j,m,n}^{i}(x,y), i = \{H,V,D\}$$





Inverse discrete wavelet transform

$$f(x, y) = \frac{1}{\sqrt{MN}} \sum_{m} \sum_{n} W_{\varphi}(j_{0}, m, n) \varphi_{j_{0}, m, n}(x, y)$$
$$+ \frac{1}{\sqrt{MN}} \sum_{i=H, V, D} \sum_{j=j_{0}}^{\infty} \sum_{m} \sum_{n} W_{\psi}^{i}(j, m, n) \psi_{j, m, n}^{i}(x, y)$$

 Like the 1-D discrete wavelet transform, the 2-D DWT can be implemented using digital filters and downsamplers. With separable two-dimensional scaling and wavelet functions, we simply take the 1-D FWT of rows of f(x, y), followed by the 1-D FWT of the resulting columns







The two-dimensional FWT — the analysis filter.







The two-dimensional FWT — the synthesis filter bank.







### Two-dimensional decomposition



### Two-scale of two-dimensional decomposition





• Example 7.12 computing a 2-D fast wavelet transform. a b





### c d

FIGURE 7.25 Computing a 2-D three-scale FWT: (a) the original image; (b) a onescale FWT; (c) a two-scale FWT; and (d) a threescale FWT.







c d e f g FIGURE 7.26 Fourth-order symlets: (a)–(b) decomposition filters; (c)-(d)reconstruction filters; (e) the one-dimensional wavelet; (f) the one-dimensional scaling function; and (g) one of three twodimensional wavelets,  $\psi^V(x, y)$ See Table 7.3 for the values of  $h_{\omega}(n)$  for  $0 \leq n \leq 7.$ 

a b





## Wavelet in image processing

- Wavelets in image processing
  - As in the Fourier domain, the basic approach is to
    - Step 1. Compute a 2-D wavelet transform of an image.
    - Step 2. Alter the transform.
    - Step 3. Compute the inverse transform.





## Wavelet in image processing

• Example 7.13 wavelet-based edge detection.







## Wavelet in image processing

Example 7.14
Wavelet-based noise
removal



a b c d e f

FIGURE 7.28 Modifying a DWT for noise removal: (a) a noisy CT of a human head; (b), (c) and (e) various reconstructions after thresholding the detail coefficients; (d) and (f) the information removed during the reconstruction of (c) and (e). (Original image courtesy Vanderbilt University Medical Center.)





## Wavelet in image compression



- Quantization  $q_j(m,n) = \operatorname{sign}(y_j(m,n)) \left| \frac{|W_j(m,n)|}{\Lambda} \right|$ 
  - uniform scalar quantization
  - separate quantization step-sizes for each subband
- Entropy coding
  - Huffman coding
  - Arithmetic coding





### Original image



DCT-based image compression



CR = 11.2460 RMS = 4.1316 Wavelet-based image compression



CR = 10.3565 RMS = 4.0104





### Original image



DCT-based image compression



CR = 27.7401 RMS = 6.9763

Wavelet-based image compression



CR = 26.4098 RMS = 6.8480





### Original image



DCT-based image compression



CR = 53.4333 RMS = 10.9662

Wavelet-based image compression



CR = 51.3806 RMS = 9.6947





# Thank You!